



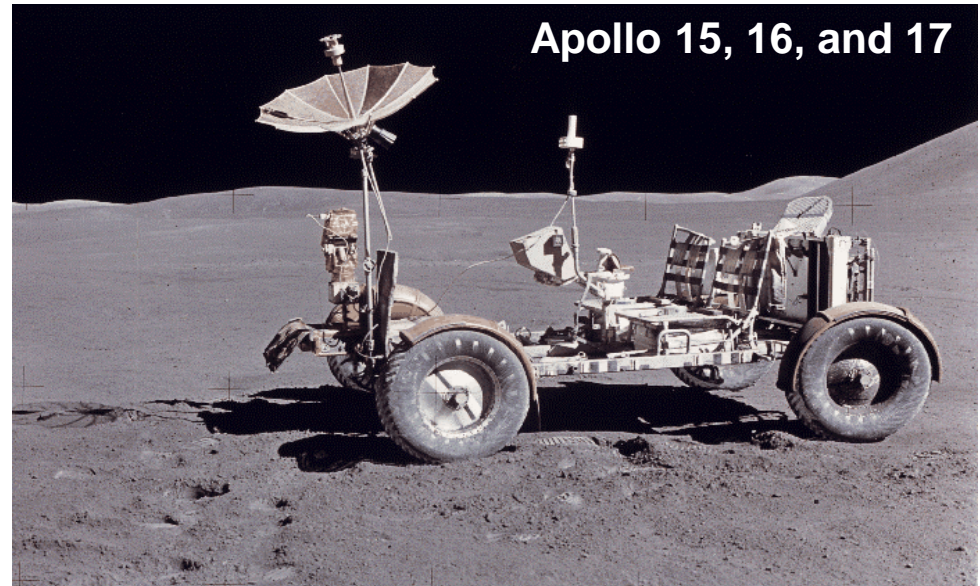
Moon Rover Thermal and Power Analysis for Night and PSR Survival



Ron Creel

Thermal & Fluids Analysis Workshop
TFAWS 2023
August 21-25, 2023
NASA Goddard Space Flight Center
College Park, MD

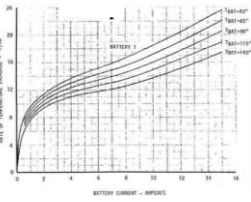
- Retired Space and Thermal Systems Engineer
- Member of the Apollo Lunar Roving Vehicle (LRV) Team



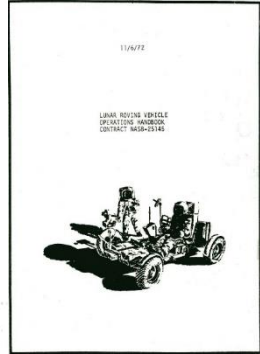
In the Beginning LRV Mission Support Thermal Modeling Was Challenging

- **1969** - Began Full Time Engineering at NASA / MSFC - Assigned to Thermal Control for Apollo LRV
- Initially Supplied Parametric Apollo 15 LRV Battery Heat Up/Cooldown Curves to Mission Control
- Chrysler Shape Factor Analyzer and Lockheed Orbital Heat Rate Package (LOHARP) Used to Calculate Sunlit Surface Radiation and Environment Parameters
 - Could Only Handle a Limited Number of Surfaces in Each Run
- PTD10 Surface Visualization Program Developed by a Colleague at NASA Marshall Space Flight Center

Battery Heat Up

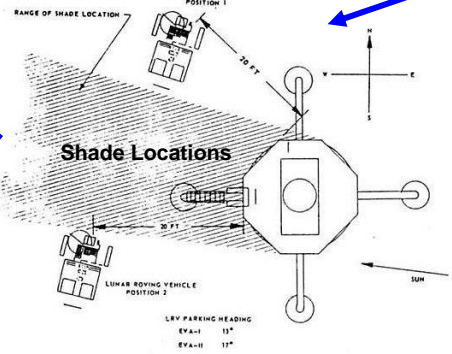


Initial Parametric Thermal Response Curves Supplied for Apollo 15 Operations Handbook

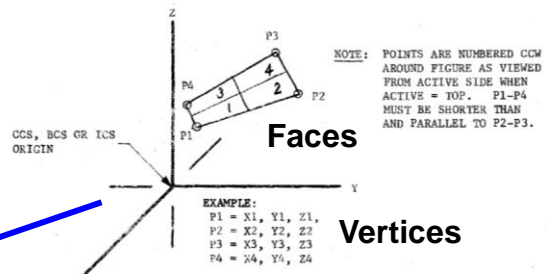


PTD10 "Wireframe" Verification Plots for Primitive Surface Models

Shadow Constraints
The LRV must not be parked in lunar shadow for longer than two hour! low temperature damage to the electronics in the control and display. Circuit breaker minimum reset time is 1 minute.



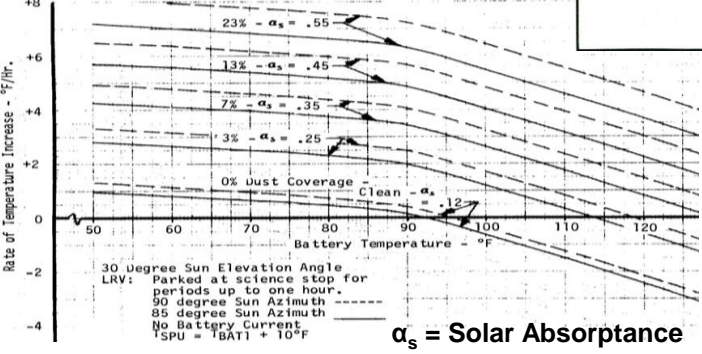
POINT METHOD



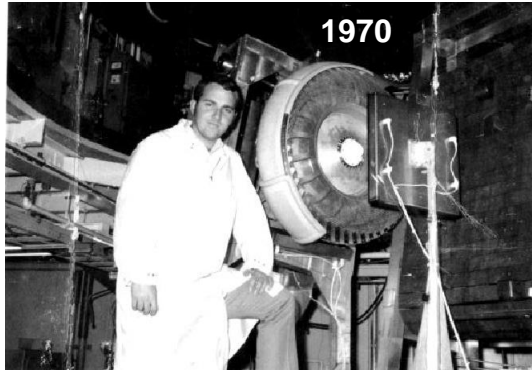
Vertices

Example Surface Polygon Input for LOHARP Trapezoid Primitives

Battery Cool Down



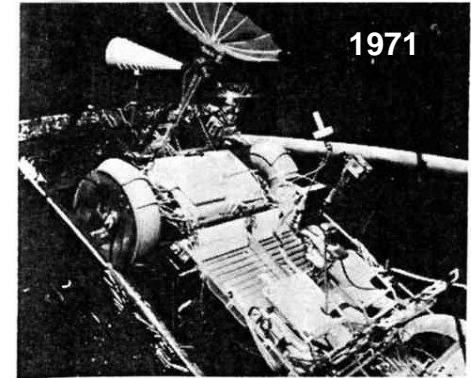
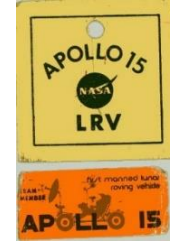
1970 - 1972



Mobility Subsystem TVAC Testing

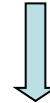
- Cumbersome 181 Node “Full” Model Correlated with TVAC* Testing Data for Apollo 15 LRV

August 1971

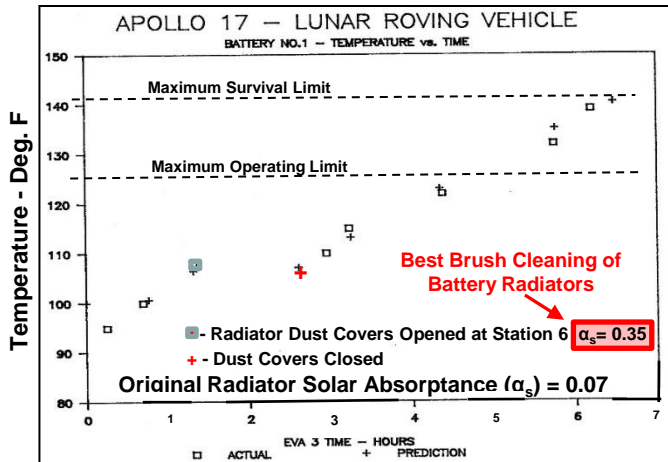


Qualification and Flight Units TVAC Testing

Apr./Dec. 1972



- 19 Node Forward Chassis, Batteries (8712 Watt-Hours), and Electronics Model Developed for Responsive Apollo 16 and 17 Support for Lunar Sunlit Morning Missions



Accurate Predictions for Realtime Mission Control



Astronauts Awarded “Silver Snoopy”



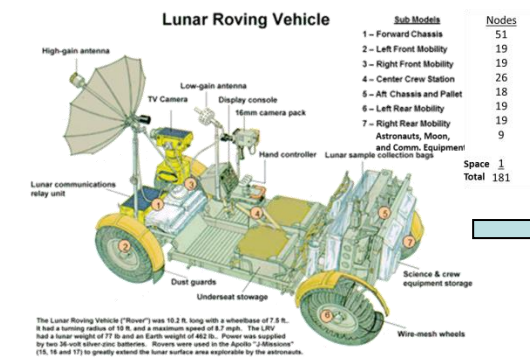
Model View Factor Verification Using Form Factometer and Lunar Module Model at U.S. Space and Rocket Center

LUROVA = Lunar ROVER Adventures
 * TVAC = Thermal VACuum

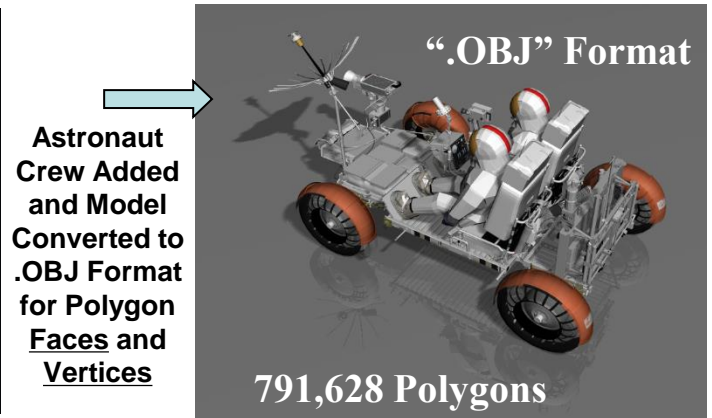
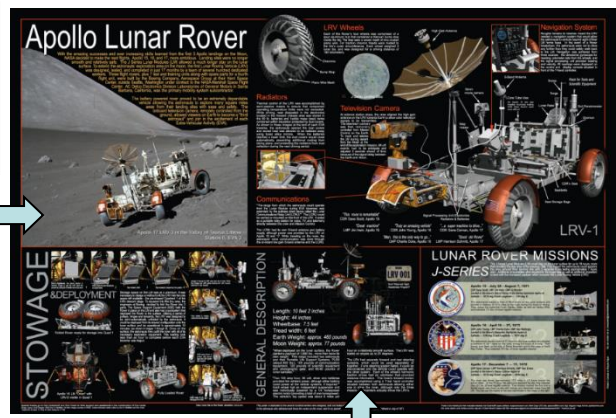
Renewed Interest in Rover Thermal Model for “Return to the Moon”

2006

- Original “Full” Rover Thermal Model Nodes and Linear Conductors List Located
- But No Surface Model for TRASYS Radiation Conductors and Solar Heat Rates
- High Quality Candidate “Lightwave” (.LWO) Rendered Polygons Used for Poster



181 Node TVAC Test Correlated NASA Rover SINDA* Thermal Model Used for Apollo 15 Mission Support



- Accurate Rover Poster and 3D Model Created by Associate Don McMillan in Ottawa, Canada
- Too Many Polygon Surfaces for NASA Thermal Radiation Analysis System (TRASYS) - 4,000 Node (Polygon) Limit, So Sub-Models Were Required

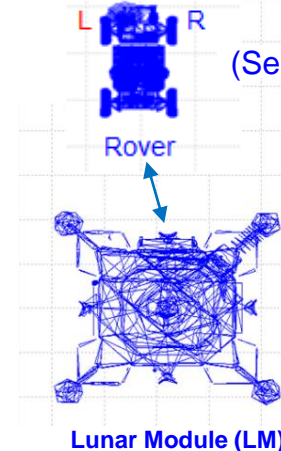
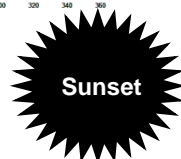
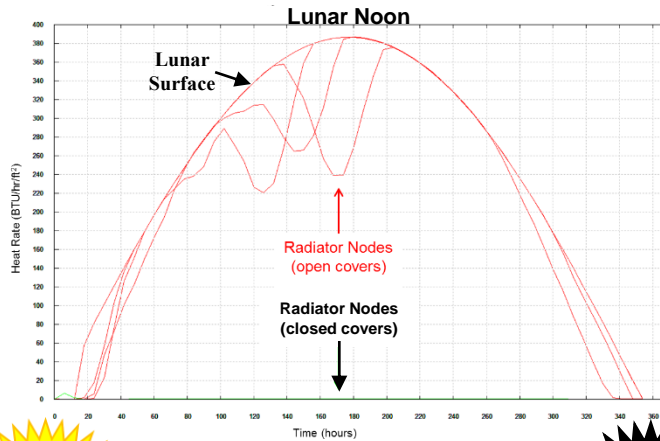
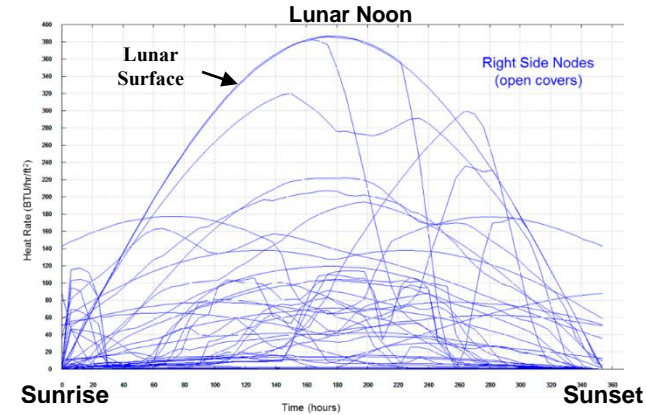
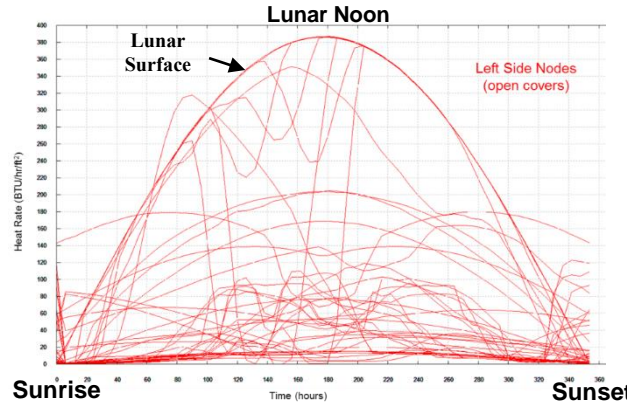
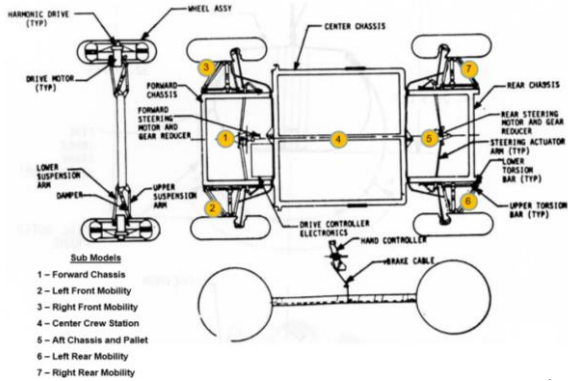
* SINDA = Systems Improved Numerical Differencing Analyzer

Example TRASYS Calculated Solar Heating for Apollo 17 at 20.16 deg. N

SURFP Subroutine Used for LRV Sub-Model Solar Heat Rates with All Surfaces Assumed Dust Covered ($\alpha_s = 0.9$)

TFAWS 2014 – August 4 -8, 2014

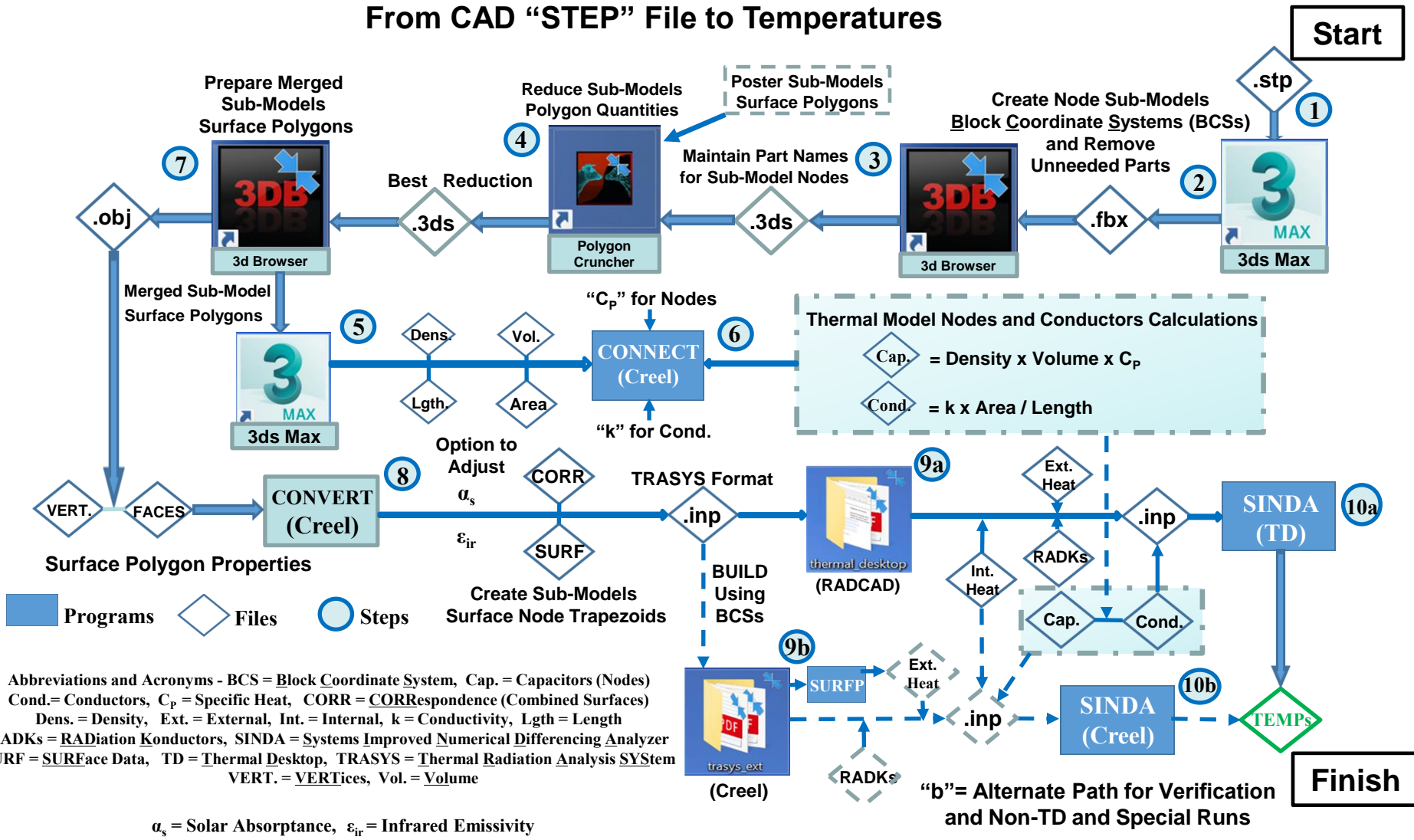
LUROVA Surface Sub Models



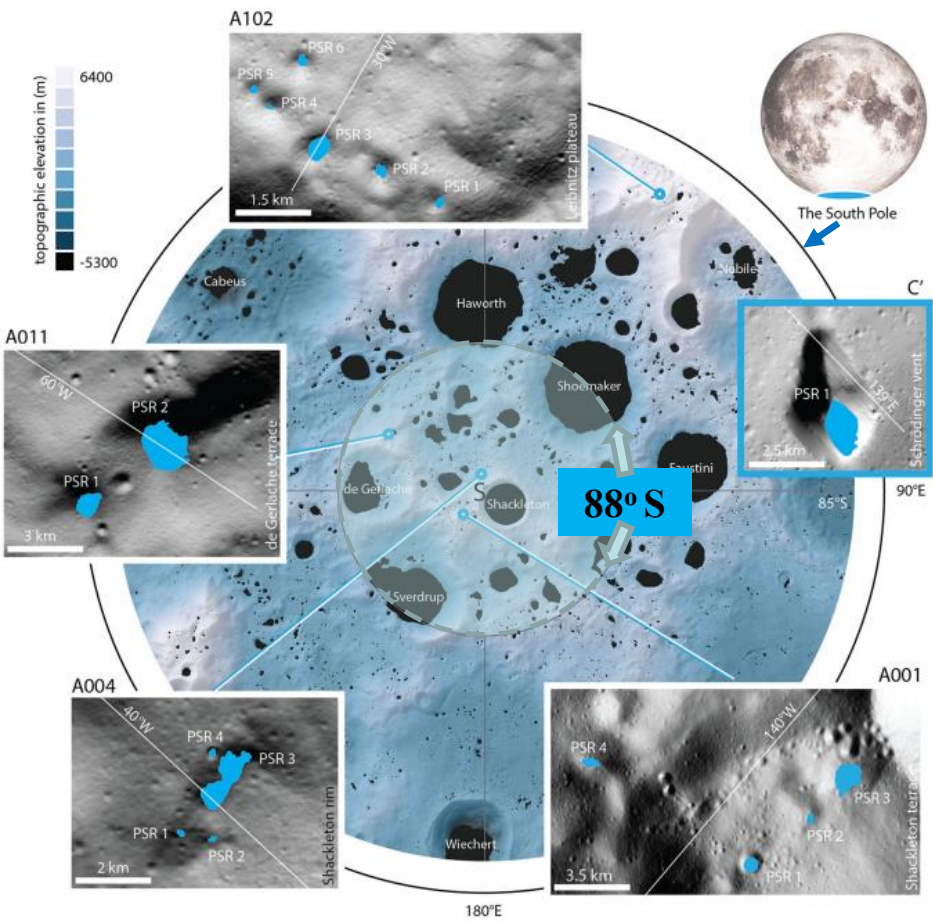
761,628 Polygons
(Separated into Sub Models and Crunched)

233,856 Polygons
(Crunched to 2000)

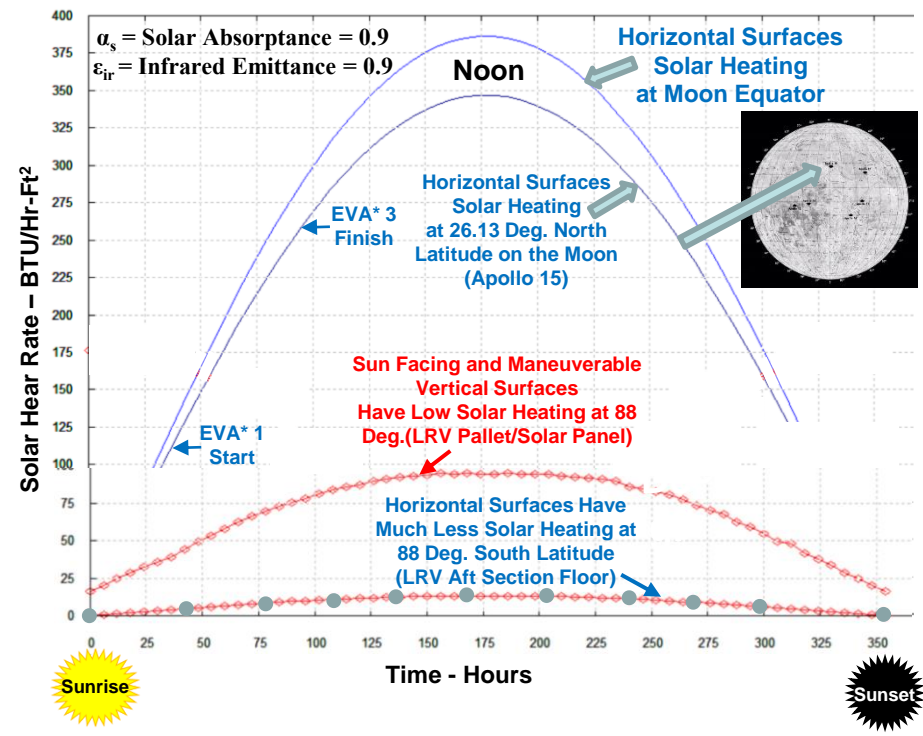
From CAD "STEP" File to Temperatures



2023



Much Lower Solar Heating in South Pole Region
 With Difficult and Risky “Chasing the Sunlight”
 Traverses for Providing Dependable Solar Power

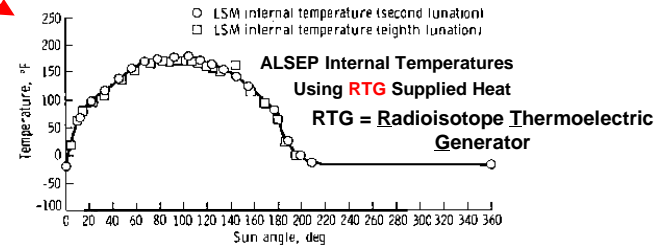
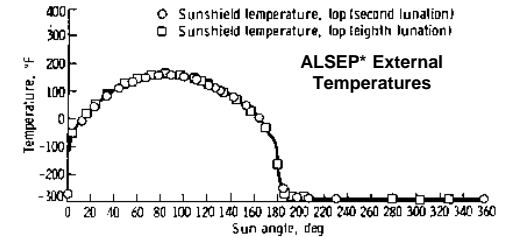
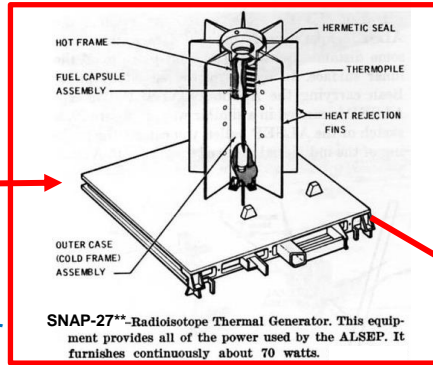
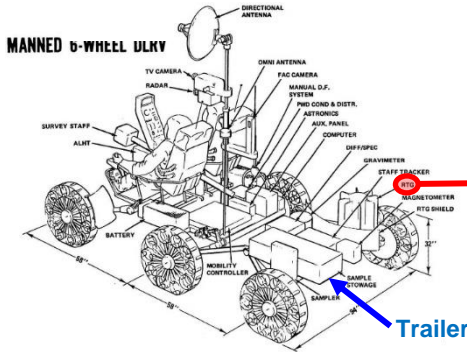


2021 Source: “Peering into Lunar Permanently Shadowed Regions with Deep Learning” (<https://www.nature.com/articles/s41467-021-25882-z>)

* EVA = Extra-Vehicular Activity

1969 - 1977

- Nuclear** Sources Studied for Apollo 18 Dual Mode Lunar Rover (DLRV) and Used on 5 ALSEPs*



- Russians Successfully Used **Nuclear** Isotope Heat Sources for Several Lunar Night Cycles on Their Lunokhod (Moonwalker) Robotic Rovers

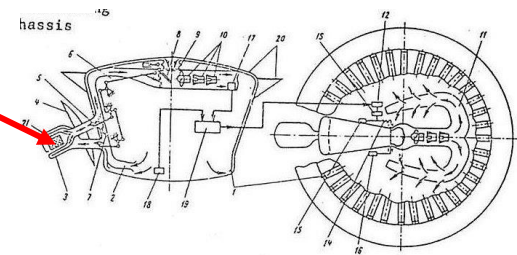
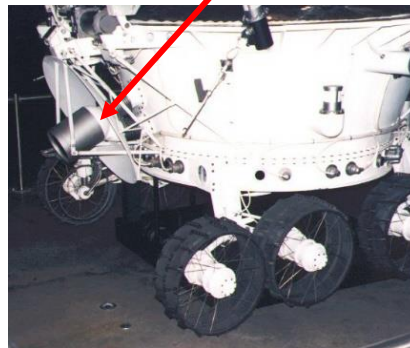
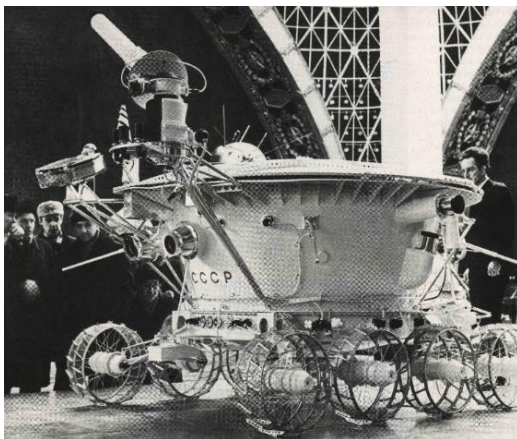


Diagram of lunokhod heat regulating system. 1) air passages of cold channel; 2) air passage of hot channel; 3) heating unit (HU); 4) HU shield; 5) HU "blinds"; 6) control of HU blinds; 7) baffle plate; 8) baffle; 9) connecting shaft; 10) three-step fan; 11) collector; 12) baffle drive; 13) step mechanism; 14) spring traction; 15) cam mechanism; 16) angular movements sensor; 17) SEL sensing element; 18) SE2 sensing element; 19) radiator-cooler; 20) collector of HU blow-off system; 21) fuel cell.

For monitoring the thermal regime aboard the lunokhod there are telemetric temperature sensors which make it possible to obtain routine information on the temperatures of all lunokhod systems during any communication session.

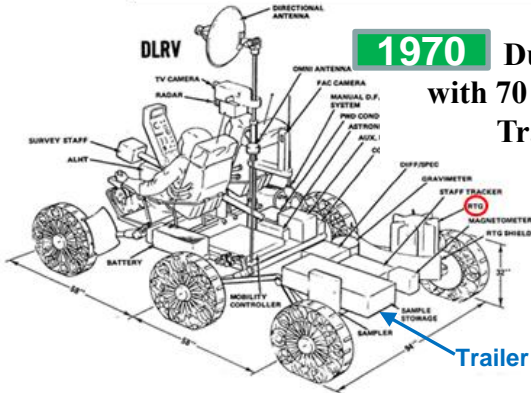
*ALSEP = Apollo Lunar Surface Experiments Package

**SNAP = System for Nuclear Auxiliary Power

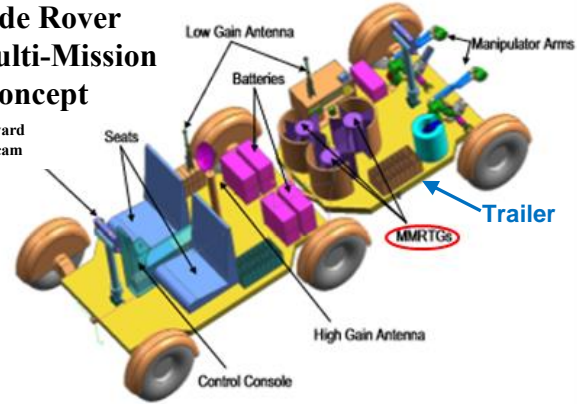
Energy Sources and Storage Studied for Extended Rover Nighttime Survival and Operation

1970 - 2018

1970 Dual Mode Rover Concept with 70 watt Nuclear RTG* on Trailer for Apollo 18



2006 - JPL** Dual Mode Rover (DMLRV) with Nuclear Multi-Mission RTGs* (MMRTGs) Concept

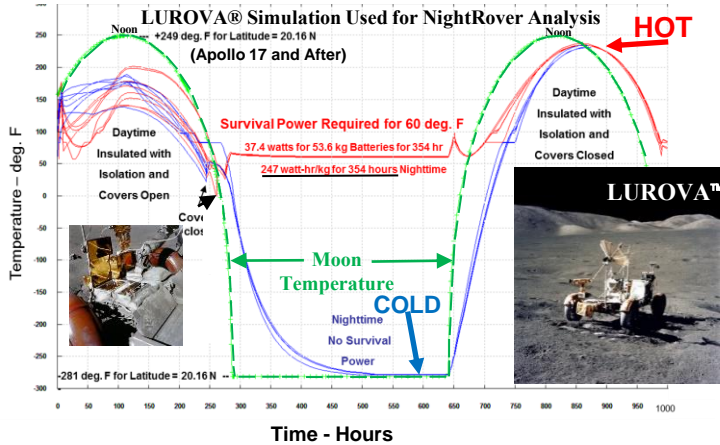


DMLRV Conceptual Design.

2004 - International Space Development Conference Panel on "Nuclear Energy for the Space Exploration Initiative"

Invited to Present Apollo LRV Thermal Experiences at Lunokhod Facility in St. Petersburg, Russia

2011-2013 - Night Rover Non-Nuclear Energy Storage Centennial Challenge (> 250 Watt-Hours/kg Desired)



2017 - 2018 - Dust and Nighttime Survival and Operation Challenges Presented in Lunar Exploration Analysis Group (LEAG) Poster and Presentation

Overview of Previous Planned Survival and Operation Through Lunar Night Periods

Two Related Primary Challenges for Successful Renewed Lunar Exploration

Challenge 1 - Coping with Exposure to Temperature Extremes (Rogent from ~100 deg. F for Sun to ~-200 deg. F for Full Moon)

Challenge 2 - Coping with Dust

Related LEAG Strategic Knowledge Gaps (SKGs)

Locations Of All Lunar Landings

USA-APOLLO MANNED LANDINGS

USA SURVEYOR UNMANNED LANDINGS

CHINA-CHANG'E UNMANNED LANDINGS

17, TBD (Limited Available Chang'e-3 and Yutu Data)

Energy for the Yutu (Lunar Rabbit) rover was provided by solar panels, allowing the rover to operate through lunar days, as well as charging its batteries. At night the rover was powered down to a large extent, and kept from getting too cold by the use of several Radioisotope Heater Units (RHUs) using plutonium-238. Due to Yutu's inability to properly orient itself from the lunar soil layer, it experienced [mobility issues](#). In early 2014 and was left unable to move across the surface. Remarkably, however, Yutu retained the ability to collect data, send and receive signals, and record images and video on well through 2015.

Besolver missions could be reactivated the following lunar day. However, damage incurred to components during the night (due to thermal loads) is possible, and may be irreversible.

Early Apollo Surface Experiments Package (EASEP), with Solar Energy/RHUs, Operated a Few Days after Apollo 11 Placement - No Nights

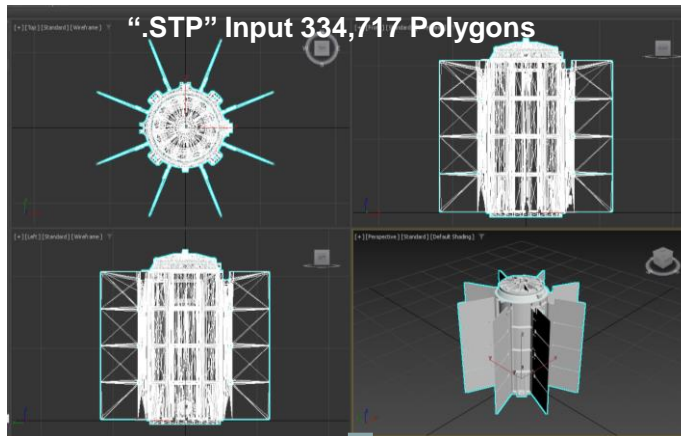
Apollo Lunar Surface Experiments Packages (ALSEPs), with Radioisotope Thermoelectric Generators (RTGs), Survived and Operated through Lunar Nights for Several Years Until Shutdown on Sept 30, 1977

* RTG = Radioisotope Thermoelectric Generator **JPL = Jet Propulsion Laboratory

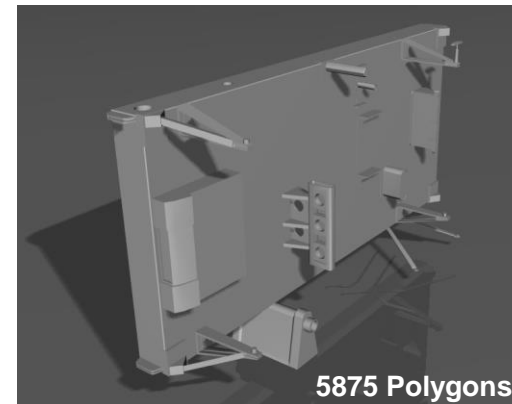
2022

LRV Aft Pallet Reduces Radiation to Crew

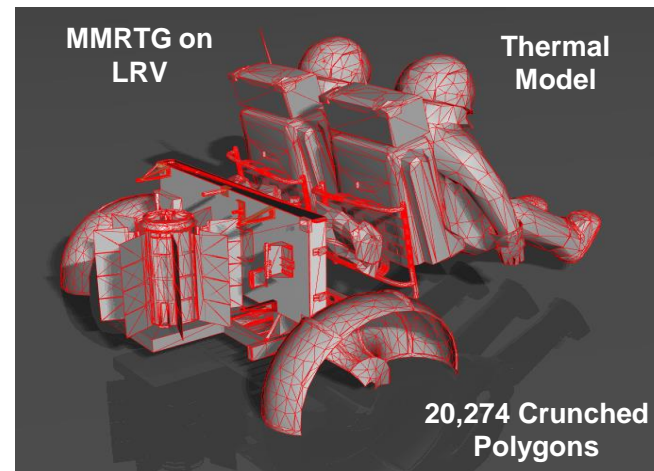
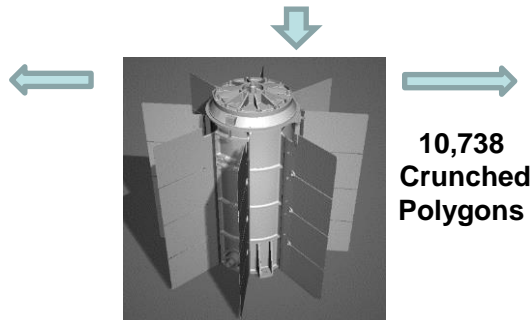
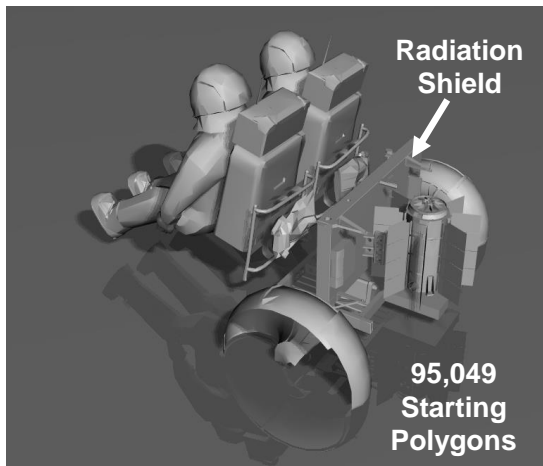
LRV Qualification Unit Aft Pallet



Aft Pallet Thermal Surface Model



JPL **MMRTG***, as Used on Mars Curiosity and Perseverance Rovers (110 Watts Continuous)

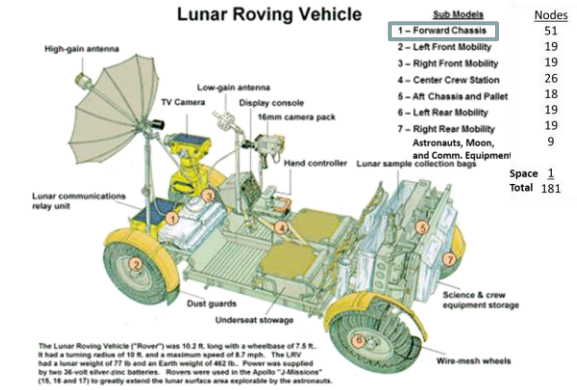


* **MMRTG** = **M**ulti **M**ission **R**adioisotope **T**hermoelectric **G**enerator

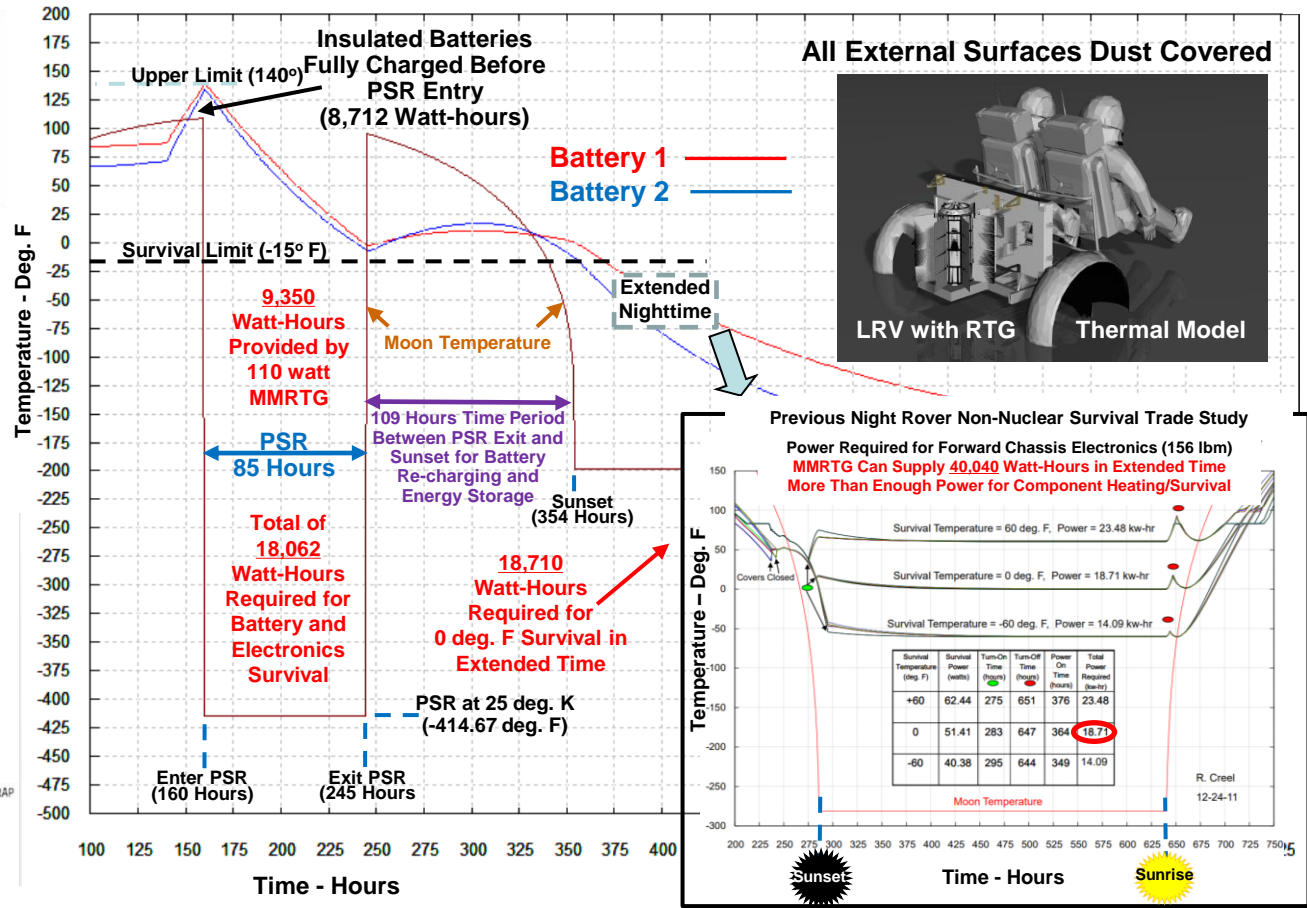
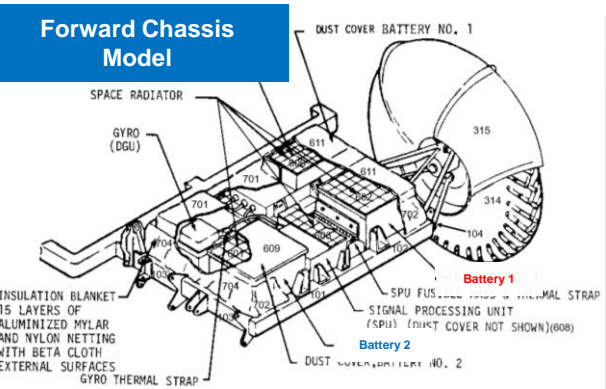
Initial Study Results - LRV Battery Temperatures for Coldest 85 Hour PSR

2022

LRV Driven and Parked at 88 deg. South Latitude with 110 Watt MMRTG Added to Battery Power in PSR



181 Node TVAC Test Correlated NASA Rover SINDA* Thermal Model Used for Apollo 15 Mission Support

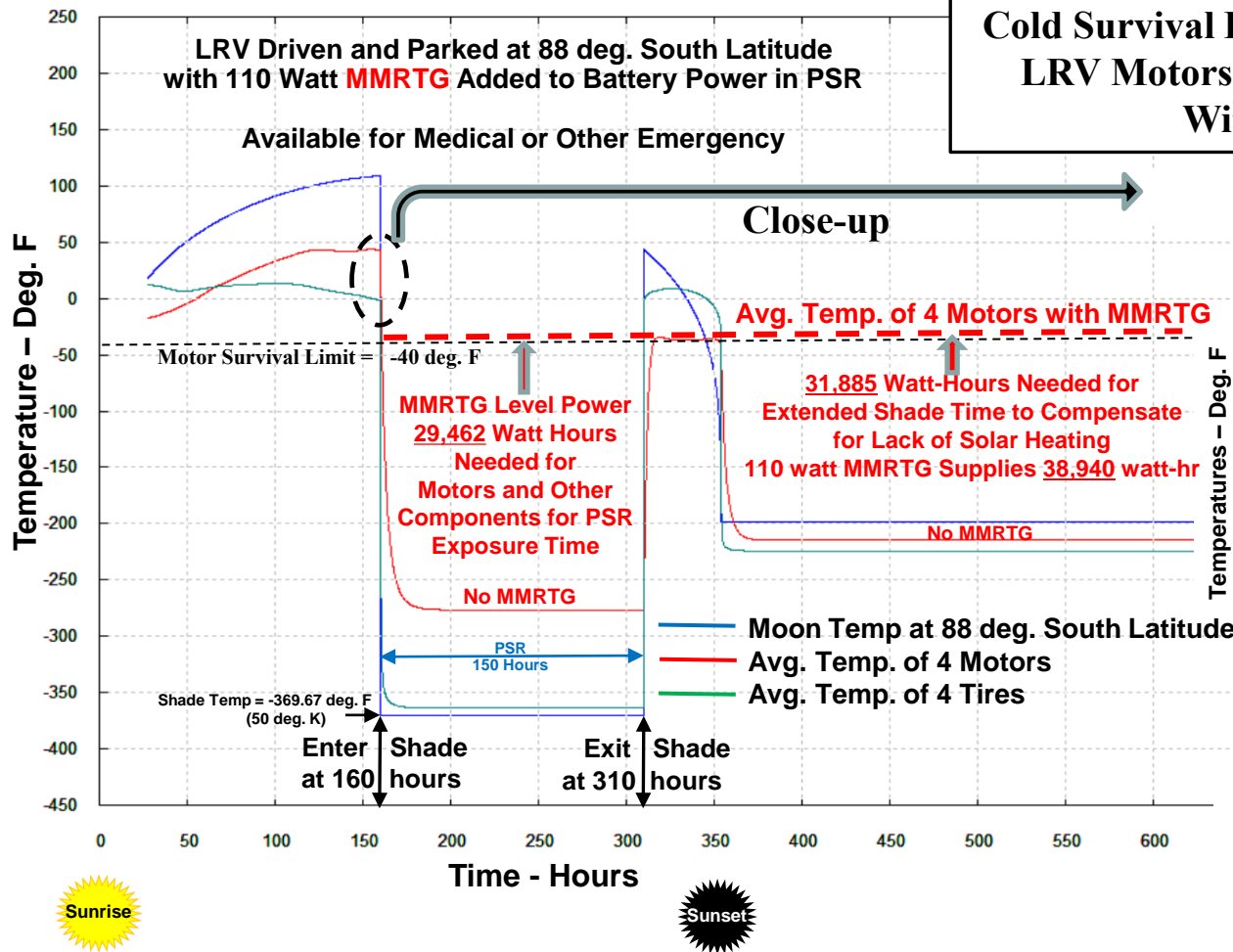


* SINDA = Systems Improved Numerical Differencing Analyzer

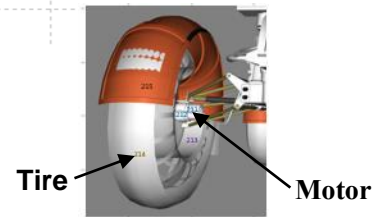
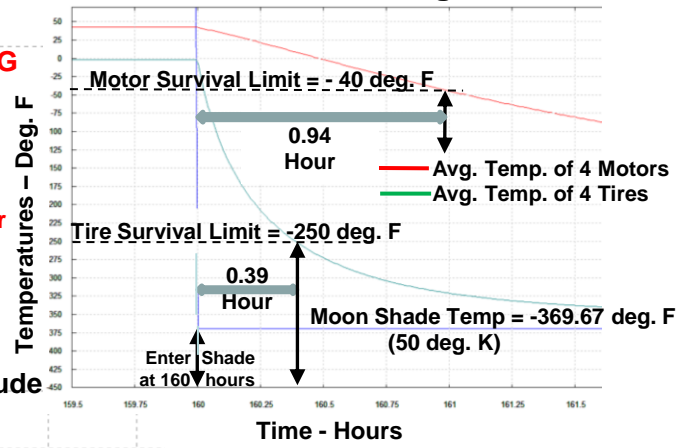
2023

150 Hours LRV Exposure in 50 Deg. K PSR

Cold Survival Limits Reached in 0.94 Hours for LRV Motors and 0.39 Hours for LRV Tires Without Heating Power



Close-up of Initial Motor/Tire Cooling in Shade Without Heating Power



Right Front Mobility Subsystem

2023

NASA LUNAR TERRAIN VEHICLE (LTV) Single Spacecraft for Ten Year Crewed and Robotic Moon Exploration



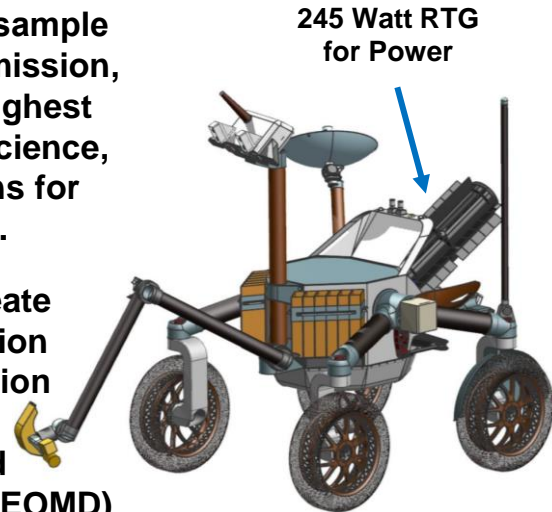
LTV “Chasing the Sunlight” Traverses Will Be Difficult and Risky, and Could be Dangerous, Especially for Emergency Need for Dependable and Immediate Energy for Transit Back to the Lunar Home Base

Requires Heavy and Maneuverable Panels for Solar Energy Collection

JPL - Endurance A Robotic Moon Rover

“Endurance is effectively a sample collection campaign in one mission, and it would address the highest priority questions in lunar science, with enormous implications for Solar System science.

Endurance-A option would create a new paradigm for collaboration between NASA’s Science Mission Directorate (SMD) and Human Exploration and Operations Mission Directorate (HEOMD) - achieving more science for less cost.”



Recommendation - Combine These Rovers to Provide Dependable and Safe Exploration Power and Gain Those Significant Cost Savings

Additional Benefit: Reduces Size/Mass of Batteries and Solar Collection Panels

2023

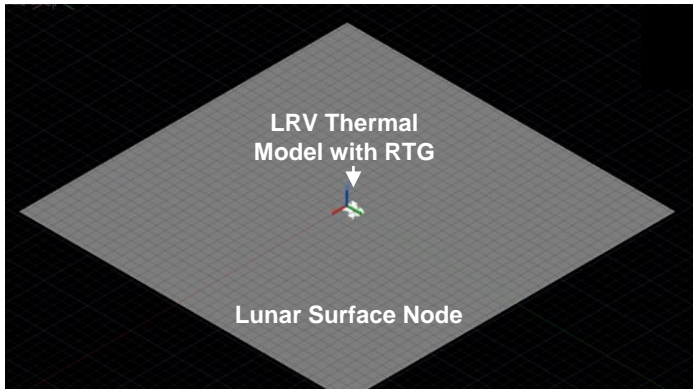
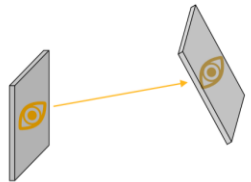
Using Radiation Shield and/or Trailer

What is the View Factor?

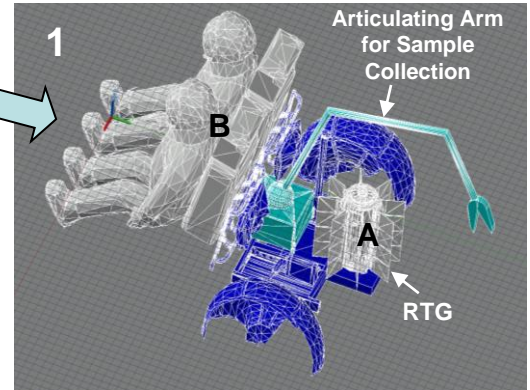
The **View Factor** is the portion of the radiative heat flux which leaves surface A that strikes surface B.

- In simpler terms, the view factor measures how well one surface can see another surface.
- View factors are purely **geometrical parameters** and are independent of the physical surface properties and temperature.

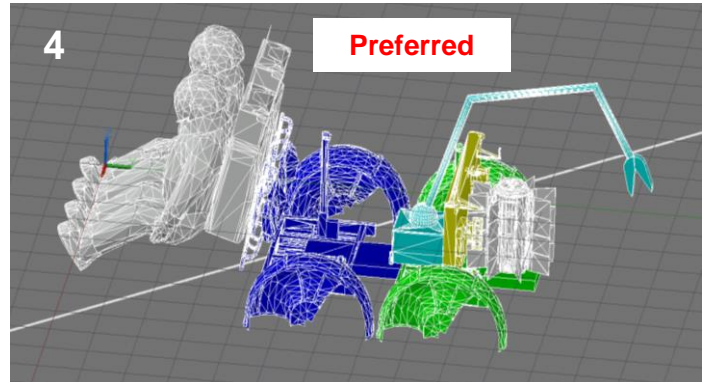
$$Q_{ij} = A_i \epsilon_i F_{ij} \sigma (T_i^4 - T_j^4)$$



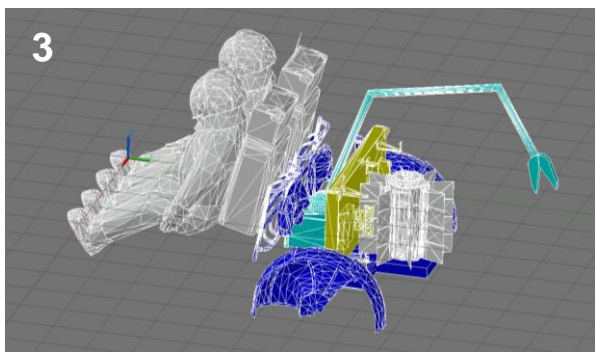
Modeled Starting with Flight Proven Apollo LRV Thermal Model With RTG Placed on LRV Aft Area Without Radiation Shield



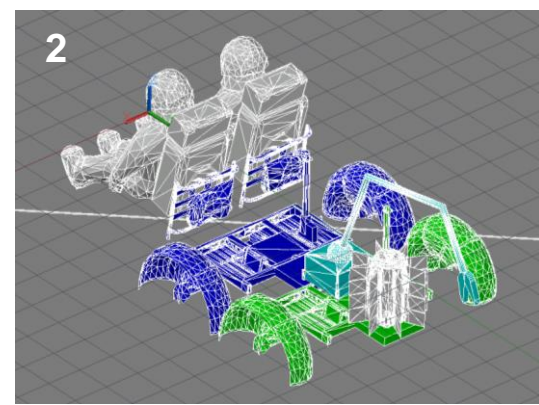
View Factor from RTG to Seated Astronauts is 0.00905 = 0.91 Percent Without Radiation Shield



Adding Aft Pallet Radiation Shield to Trailer Reduces the View Factor from the RTG to Seated Astronauts to 0.0 = 0.0 Percent



Adding a Radiation Shield Using a LRV Aft Pallet Reduces the View Factor from the RTG to Seated Astronauts to 0.001023 = 0.10 Percent



Moving RTG to Trailer Reduces View Factor from RTG to Seated Astronauts to 0.002345 = 0.23 Percent



Summary



- **Lunar Rovers Greatly Increased Science Accomplishments on Apollo 15, 16, and 17 Missions**
 - **Included Very Important Evolution of Accurate Visible Thermal Models for Mission Support**
 - **Accurate Rover Thermal Surface Modeling Has Improved Over the Past 54 Years**
 - **Mostly Automated Surface Handling Process Developed Using 4 Commercially Available Software Programs : 3ds Max, 3d Browser, Polygon Cruncher, and Thermal Desktop**
- **Radioisotope Thermoelectric Generator Recommended for New Artemis Lunar Terrain Vehicle**
 - **Would be a Valuable Addition If Presently Planned “Chasing the Sunlight” is Not Achievable**
 - **Combining the “Endurance” RTG with the LTV Can Reduce Exploration Costs and Provide Important Immediately Available Power for Emergencies**
 - **Would Reduce Size/Mass of Batteries and Maneuverable Solar Energy Collection Panels**

Bottom Line : Let’s Get These Rovers Combined for Safe and Reliable South Pole Science Exploration on the Moon

